

### Rotary actuator fail-safe for butterfly valves

Torque motor 160 Nm

Nominal voltage AC 24...240 V /

- DC 24...125 V
- Control modulating, communicative, hybrid
- with 2 integrated auxiliary switches
- Conversion of sensor signals

• Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control

Data

# **Technical data sheet**

# PRKCA-BAC-S2-T



## **Technical data**

Electrical data	Nominal voltage	AC 24240 V / DC 24125 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2264 V / DC 19.2137.5 V
	Power consumption in operation	52 W
	Power consumption in rest position	9 W
	Power consumption for wire sizing	with 24 V 54 VA / with 240 V 68 VA
	Power consumption for wire sizing note	Imax 20 A @ 5 ms
	Auxiliary switch	2 x SPDT, 1 x 10° / 1 x 090° (default setting 85°)
	Switching capacity auxiliary switch	1 mA3 A (0.5 A inductive), AC 250 V
	Connection supply	Terminals 2.5 mm <sup>2</sup>
	Connection protective earth	earth terminal
	Connection control	Terminals 1.5 mm <sup>2</sup>
	Connection auxiliary switch	Terminals 2.5 mm <sup>2</sup>
	Parallel operation	Yes (note the performance data)
l bus communication	Communicative control	BACnet MS/TP Modbus RTU MP-Bus
	Number of nodes	BACnet / Modbus see interface description MP-Bus max. 8
Functional data	Torque motor	160 Nm
	Operating range Y	210 V
	Input Impedance	100 kΩ
	Operating range Y variable	0.510 V
		420 mA
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	0.510 V
	Setting fail-safe position	0100%, adjustable with Belimo Assistant App (default setting 0%)
	Bridging time (PF)	2 s
	Bridging time (PF) variable	010 s
	Position accuracy	±5%
	Manual override	hand lever
	Running time motor	35 s / 90°
	Running time motor variable	30120 s
	Running time fail-safe	30 s / 90°
	Sound power level, motor	68 dB(A)
	Sound power level, fail-safe	61 dB(A)
	Position indication	Mechanically (integrated)



Safety data	Protection class IEC/EN	I, protective earth (PE)
	Protection class UL	I, protective earth (PE)
	Degree of protection IEC/EN	IP66/67
	Degree of protection NEMA/UL	NEMA 4X
	Enclosure	UL Enclosure Type 4X
	EMC	CE according to 2014/30/EU
	Low voltage directive	CE according to 2014/35/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1
		The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Mode of operation	Type 1.AA
	Rated impulse voltage supply	4 kV
	Rated impulse voltage control	0.8 kV
	Rated impulse voltage auxiliary switch	2.5 kV
	Pollution degree	3
	Ambient humidity	Max. 100% RH
	Ambient temperature	-3050°C [-22122°F]
	Storage temperature	-4080°C [-40176°F]
	Servicing	maintenance-free
Mechanical data	Connection flange	F07 (F05/F10 only with accessory)
Weight	Weight	6.5 kg
Terms	Abbreviations	POP = Power off position / fail-safe position CPO = Controlled power off / controlled fail- safe PF = Power fail delay time / bridging time

### Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Caution: Power supply voltage!
- The device has a protective earthing. Incorrect connection of the protective earth can lead to hazards due to electrical shock.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- Apart from the connection box, the device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
- · The two switches integrated in the actuator are to be operated either on power supply voltage or at safety extra-low voltage. The combination power supply voltage/safety extra-low voltage is not permitted.

### **Product features**

**Fields of application** 

The actuator is particularly suitable for utilisation in outdoor applications and is protected against the following weather conditions:

- UV radiation
- Dirt / Dust
- Rain / Snow
- Air humidity



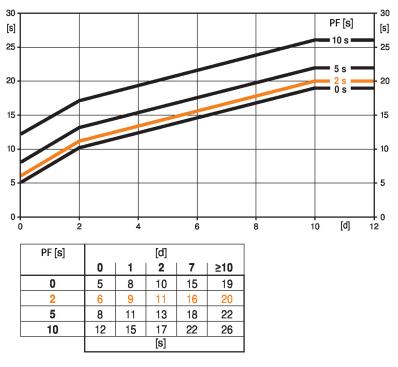
#### Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position.

The duration of the pre-charging time depends mainly on following factors:

- Duration of the power failure
- PF delay time (bridging time)

Typical pre-charging time



[d] = Electricity interruption in days [s] = Pre-charging time in seconds PF[s] = Bridging time Calculation example: Given an electricity interruption of 3 days and a bridging time (PF) set at 5 s, the actuator requires a precharging time of 14 s after the electricity has been reconnected (see graphic).

**Delivery condition (capacitors)** 

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 20 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

Bridging time	Electrical interruptions can be bridged up to a maximum of 10 s.
	In the event of a power failure, the actuator will remain stationary in accordance with the set bridging time. If the power failure is greater than the set bridging time, then the actuator will move into the selected fail-safe position.
	The pre-programmed bridging time is set to 2 s. This can be modified on site in operation with the use of the "Belimo Assistant App".
Setting fail-safe position (POP)	The desired fail-safe position can be set 0100% with the "Belimo Assistant App" or ZTH EU. The setting always refers to the adapted angle of rotation range. In the event of a power failure, the actuator will move into the selected fail-safe position.
Converter for sensors	Connection option for two sensors (passive, active or switching contacts). In this way, the analogue sensor signal can be easily digitised and transferred to the bus systems BACnet or Modbus.
Internal heating	An internal heater prevents condensation buildup.
	Thanks to the integrated temperature and humidity sensor, the built-in heater automatically switches on/off.
Parametrisable actuators	The factory settings cover the most common applications.
	The Belimo Assistant App is required for parametrisation via Near Field Communication (NFC) and simplifies commissioning. Moreover, it provides a variety of diagnostic options.
	The ZTH EU service tool provides a selection of both diagnostic and setting options.
Combination analogue - communicative (hybrid mode)	With conventional control by means of an analogue control signal, BACnet or Modbus can be used for the communicative position feedback



Simple direct mounting	Simple direct mounting on the butterfly valve. The mounting orientation in relation to the butterfly valve can be selected in 90° (angle) increments.
Manual override	The valve can be manually operated using a hand crank. Unlocking is carried out manually by removing the hand crank.
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Flexible signalling	The actuator has one auxiliary switch with a fixed setting (10°) and one adjustable auxiliary switch (090°).

## Accessories

Electrical accessories	Description	Туре
	Signal converter voltage/current 100 k $\Omega$ 420 mA, Supply AC/DC 24 V	Z-UIC
Mechanical accessories	Description	Туре
	Position indicator and tappet shaft, F07, square 45° offset, SW 17, DN 125300	ZPR01
	Tappet shaft, F07, square 45° offset, SW 17	ZPR02
	Position indicator and tappet shaft, F05, square 45° offset, SW 14, DN 80100	ZPR03
	Retrofit adapter kit, F07/F10 (incl. screws F07), flat head/square, SW 17	ZPR05
	Retrofit adapter kit, F07/F10 (incl. screws F07), square 45° offset, SW 14	ZPR06
	Adapter kit with spacer ring, F07, square 45° offset, SW 17	ZPR08
	Retrofit adapter kit, F07/F05/F10 (incl. screws F07), flat head/square, SW 14	ZPR09
	Retrofit adapter kit, F05/F07/F10 (incl. screws F05), flat head/square, SW 14	ZPR10
	Retrofit adapter kit, F07/F10 (incl. screws F07), square 45° offset, SW 18	ZPR11
	Retrofit adapter kit, F07/F10 (incl. screws F07), flat head/square, SW 16	ZPR12
	Retrofit adapter kit, F07/F05/F10 (incl. screws F07), flat head/square, SW 11	ZPR13
	Retrofit adapter kit, F07/F05/F10 (incl. screws F07), flat head/square, SW 12.7	ZPR14
	Retrofit adapter kit, F07/F10 (incl. screws F07), square 45° offset, SW 11	ZPR15
	Hand crank for PR/PM actuator	ZPR20
	Spacer ring, F04/F05, Height 22 mm	ZRI-001
	Spacer ring, F05/F07, Height 23.5 mm	ZRI-002
Tools	Description	Туре
	Belimo Assistant App, Smartphone app for easy commissioning,	Belimo Assistant
	parametrising and maintenance	Арр
	Converter Bluetooth / NFC	ZIP-BT-NFC
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance	ZTH EU
	devices Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
Sensors	Description	Туре
	Duct/Immersion sensor Temperature 50 mm x 6 mm Pt1000	01DT-1BH
	Duct/Immersion sensor Temperature 50 mm x 6 mm Ni1000	01DT-1CH
	Duct/Immersion sensor Temperature 100 mm x 6 mm Pt1000	01DT-1BL
	Duct/Immersion sensor Temperature 100 mm x 6 mm Ni1000	01DT-1CL
	Duct/Immersion sensor Temperature 150 mm x 6 mm Pt1000	01DT-1BN
	Duct/Immersion sensor Temperature 150 mm x 6 mm Ni1000	01DT-1CN
	Duct/Immersion sensor Temperature 200 mm x 6 mm Pt1000	01DT-1BP
	Duct/Immersion sensor Temperature 200 mm x 6 mm Ni1000	01DT-1CP
	Duct/Immersion sensor Temperature 300 mm x 6 mm Pt1000	01DT-1BR
	Duct/Immersion sensor Temperature 300 mm x 6 mm Ni1000	01DT-1CR
	Dust/Immersion concer Temperature 450 mm v 6 mm Bt1000	01DT 1DT
	Duct/Immersion sensor Temperature 450 mm x 6 mm Pt1000 Duct/Immersion sensor Temperature 450 mm x 6 mm Ni1000	01DT-1BT





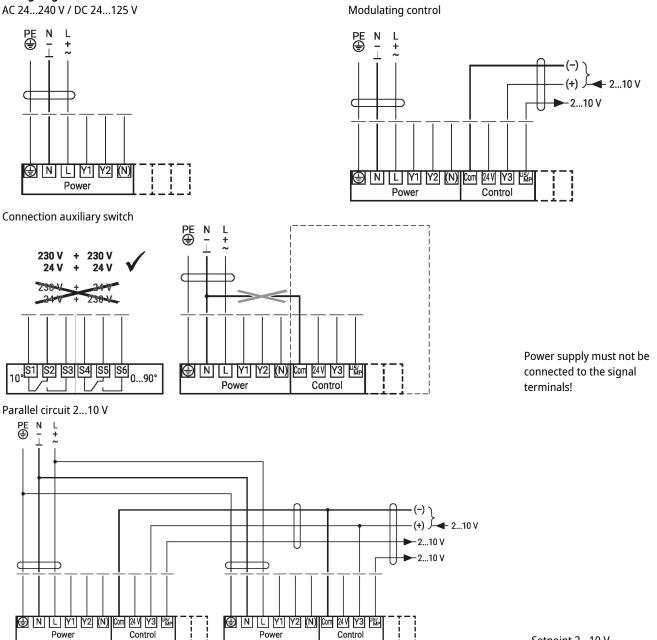
Caution: Power supply voltage!

applicable RS-485 regulations.

Parallel connection of other actuators possible. Observe the performance data.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with

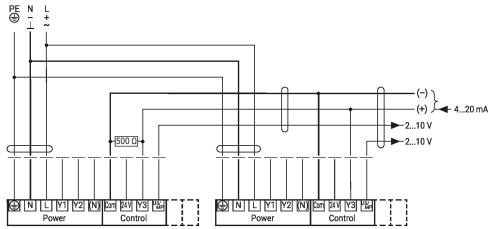
Wiring diagrams



Setpoint 2...10 V

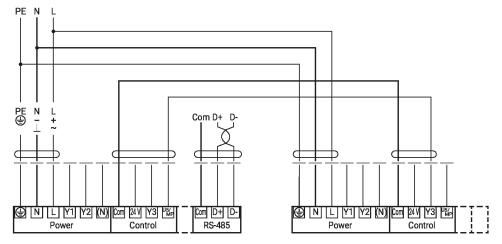


### Parallel circuit 4...20 mA



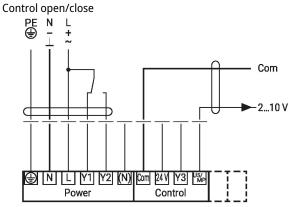
Setpoint 2...10 V

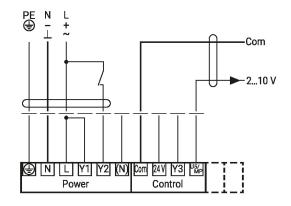
Connection BACnet MS/TP / Modbus RTU with analogue follow-up



## Functions

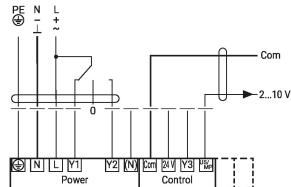
### Functions with specific parameters (NFC)



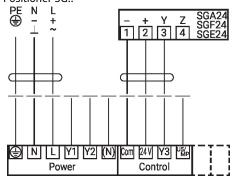




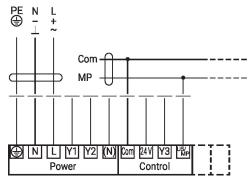
# Control 3-point



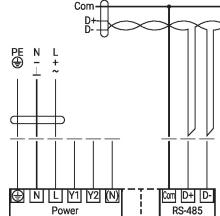
Positioner SG..



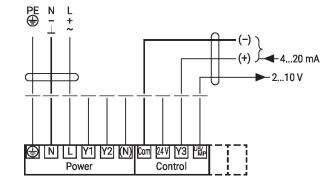
Connection on the MP-Bus



Connection BACnet MS/TP / Modbus RTU



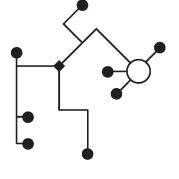
Control 4...20 mA



### Note

Maximum output power «DC 24 V out» 1.2 W @ 50 mA! A separate isolating transformer must be used for higher performance!

MP-Bus Network topology



Com D+ D-

RS-485

There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).

Supply and communication in one and the same 3-wire cable • no shielding or twisting necessary

• no terminating resistors required

N \_\_\_\_\_

L + ~

L Y1 Y2 (N

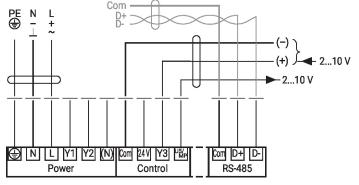
Power

PE

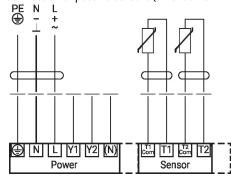
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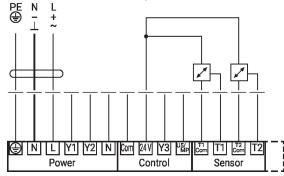
### Connection BACnet MS/TP / Modbus RTU with analogue setpoint (hybrid mode)



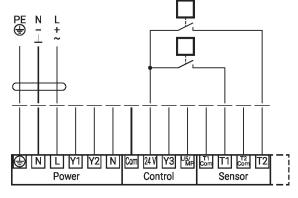
Connection of passive sensors (BACnet MS/TP / Modbus RTU)



Connection of active sensors (BACnet MS/TP / Modbus RTU)



Switching contact connection (BACnet MS/TP / Modbus RTU)



1)	2)
200 Ω2 kΩ	0.1 Ω
2 kΩ10 kΩ	1Ω
10 kΩ55 kΩ	10 Ω

1) Resistance range 2) Resolution Compensation of the measured value is recommended - Suitable for Ni1000 and Pt1000

- Suitable Belimo types 01DT-..

Possible input voltage range: DC 0...10 V (resolution 5 mV) To capture for example:

- Active temperature sensors

- Flow sensors

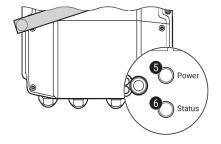
- Pressure / differential pressure sensors

Requirements for switching contact: The switching contact must be able to accurately switch a current of 10 mA @ 24 V. To capture for example: - Flow monitors - Operation / malfunction

messages of chillers



## Operating controls and indicators



### **5** Push-button and LED display green

Off:	No power supply or malfunction
On:	In operation
Press button:	Triggers test run, followed by standard mode

### 6 Push-button and LED display yellow

Off:	Standard mode
On:	Test run active
Flickering:	BACnet / Modbus communication active
Flashing:	Request for addressing from MP client
Press	Confirmation of the MP addressing
button:	

#### Auxiliary switch settings

**Note:** Perform settings on the actuator only in deenergised state.

For the auxiliary switch position settings, carry out points 1 to 4 successively.

### **1** Gear train disengagement

Opening the manual override cover and adjusting the hand crank. Manual override is possible.

#### 2 Manual override

Turn the hand crank until the desired switching position **A** is indicated and then remove the hand crank.

## 3 Auxiliary switch

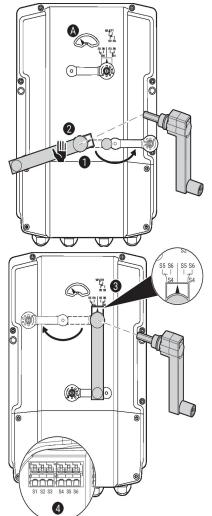
For the auxiliary switch position settings, carry out points 1

to 4 successively. Opening the auxiliary switch adjustment cover and adjusting the hand crank. Turn the hand crank until the arrow points to the vertical line.

### 4 Terminals

Connect continuity tester to S4 + S5 or to S4 + S6.

If the auxiliary switch should switch in the opposite direction, rotate the hand crank by 180°.







**NFC connection** Belimo devices marked with the NFC logo can be operated with the Belimo Assistant App.

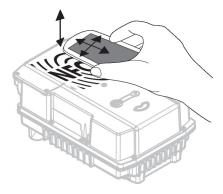
Requirement:

- NFC- or Bluetooth-capable smartphone

- Belimo Assistant App (Google Play & Apple AppStore)

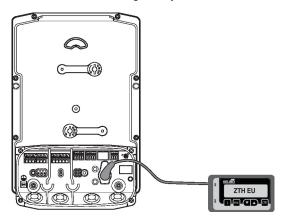
Align NFC-capable smartphone on the device so that both NFC antennas are superposed.

Connect Bluetooth-enabled smartphone via the Bluetooth-to-NFC Converter ZIP-BT-NFC to the device. Technical data and operation instructions are shown in the ZIP-BT-NFC data sheet.



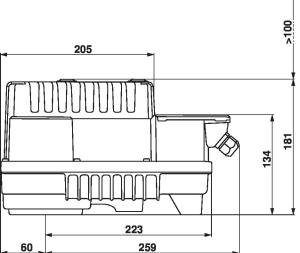
#### **Tools connection**

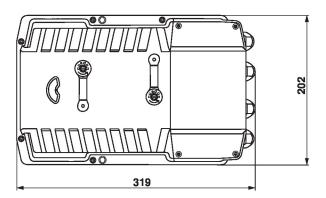
The actuator can be configured by the ZTH EU via the service socket.











### **Further documentation**

- Tool connections
- BACnet Interface description
- Modbus Interface description
- Overview MP Cooperation Partners
- Introduction to MP-Bus Technology
- MP Glossary
- The complete product range for water applications
- Data sheets for butterfly valves
- Installation instructions for actuators and/or butterfly valves
- General notes for project planning